

## Connections

Reference the figure at right.

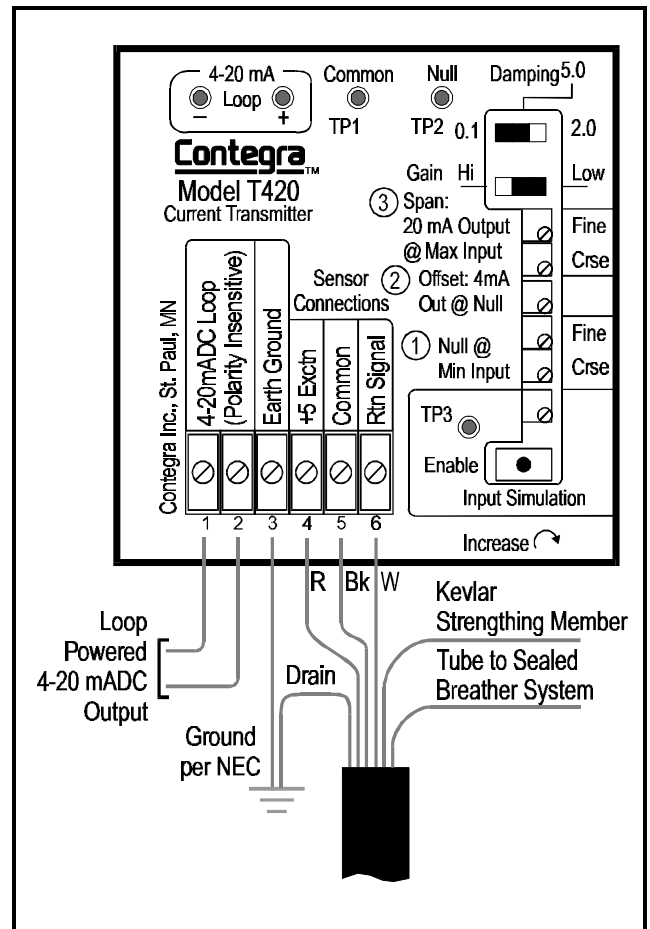
- Terminal 3 (EARTH GROUND) must be grounded per the National Electric Code (NEC). Failure to properly ground the T420 voids the warranty.
- A twisted-pair cable (20 AWG min.) is required for best performance. Use metal conduits to isolate signal wiring from electrically noisy environments.
- The 4-20 mADC loop must be powered by a UL approved Class 2 supply.
- The T420 (terminals 1 & 2) requires a minimum of 12 VDC (the lift-off voltage) and accepts a maximum of 40 VDC. The Class 2 power supply must be sized to accommodate the sum of the loop resistance and the in-circuit resistance of all connected controllers.
  - The Min voltage = 12 VDC + (resistance X 0.02)
  - The Max voltage = 40 VDC + (resistance X 0.02)
  - The Max load = (supply voltage - 12) X 50

The maximum load includes loop resistance and the resistance of all connected equipment.

## Benchtop Cal

(w/Cal Stand)

- Apply the "zero scale" pressure to the sensor (i.e. the pressure at which 4 mA is to be transmitted).
- Measure the voltage from TP1 (common) to TP2 (Null).
- Adjust the potentiometers labeled "**Null @ Min Input**" (course and fine) until zero volts is measured between TP1 and TP2.
- Monitor the 4-20 mADC loop current<sup>1</sup>. (Placing the DVM's probes in the T420's 4-20 mADC test points found in the upper left corner of the transmitter.)
- Adjust the potentiometer labeled "**Offset: 4 mA Out @ Null**" until 4 mA is measured.
- Apply full-scale pressure to the sensor.
- Adjust the potentiometers labeled "**Span: 20 mA Output @ Max Input**" (course and fine) until 20 mA is measured. (If a small excursion is being measured, the "gain" jumper may need to be moved to the "Hi" setting to achieve the required 20 mA output.)
- Finally, choose the desired Damping time constant. Three time constants are available: 0.1 (jumper @ left), 2.0 (jumper @ right) and 5.0 (jumper re-



moved) seconds.

## Simulated Calibration

The T420 contains on-board input simulation circuitry. The simulation feature allows the installing technician to perform a simulated calibration prior to installation. The simulated calibration is performed as follows:

- Connect the transducer to the T420, leaving the sensor unpressurized (i.e. out of the sensed media) and in a vertical orientation. In this condition the transducer is generating its 'zero-pressure' output.
- Measure the voltage from TP1 (common) to TP2 (Null).
- Adjust the potentiometers labeled "Null @ Min Input" (course and fine) until zero volts is measured.

## T420 Calibration

4. Typically the transducer is subjected to only a percentage of its full pressure rating. The installing technician must calculate the maximum percentage or "Max %". The equation is shown below:

$$\text{Max\%} = \left[ \frac{\text{Max Sensed Height}}{\text{Sensor's Max Output}} \right] \text{ Equation 1}$$

(Sensor's Max Output = Sensor's PSI \* 2.31<sup>2</sup>)

e.g. for a 10' wet well using a 5 psi sensor, Max% is:

$$\text{Max\%} = 10 / (5 * 2.31^2) = 0.8670$$

5. Calculate the Full Scale Output (FSO) as follows:

$$\text{FSO} = ( 4 * \text{Max\%} ) + .5 \text{ Equation 2}$$

e.g. continuing the above example of a 10' wet well using a 5 PSI sensor, the 0.8670 is inserted into the formula.

$$\text{FSO} = ( 4 * 0.8670 ) + .5 = 3.968 \text{ VDC}^3$$

Using this information:

6. Connect a voltmeter to TP1 (common) and TP3 (Input Simulation Level).
7. While pressing the Input Simulation pushbutton, adjust the Input Simulation potentiometer until the calculated full-scale simulation voltage (FSO as calculated above) is measured. Release the pushbutton.
8. Monitor the 4-20 mADC loop current by placing the DVM's probes in the T420's test points - located in the upper left corner.
9. Adjust the potentiometer labeled "**Offset: 4 mA Output @ Null**" until 4 mA is measured.
10. Press the Input Simulation pushbutton and thus apply the simulated full-scale signal. Adjust the potentiometers labeled "**Span: 20 mA Output @ Max Input**" (Course & Fine) until the DVM measures 20 mA.
11. Finally, choose the desired Damping time constant. Three time constants are available: 0.1 (jumper @ left), 2.0 (jumper @ right) and 5.0 (jumper removed) seconds.

### Example 1

A 5 PSI sensor has a maximum range of 11.53 feet (5 PSI \* 2.31<sup>2</sup> Ft./PSI). If the maximum level to be measured is 8 feet, the percentage is a portion of that range calculated by dividing 8 by the full scale range of 11.53 (e.g. 8/11.53 = 69.38% = Max%). In this case the sensor's 'full scale' output, based upon the above information and Equation 2 is calculated as follows:

$$\text{FSO} = ( 4 * 0.6938 ) + 0.5$$

or

$$\text{FSO} = 2.28 \text{ VDC at 8 ft.}$$

### Example 2

A 15 PSI sensor has a maximum range of 34.6 feet (15 PSI \* 2.31<sup>2</sup> Ft./PSI). If the maximum level to be measured is 17 feet, the Max% is 49.13 % (17 ft / 34.6 ft.) In this case the sensor's 'full scale' output is calculated as follows:

$$\text{FSO} = ( 4 * 0.4913 ) + 0.5$$

or

$$\text{FSO} = 2.47 \text{ VDC at 17 ft.}$$

#### NOTES:

- 1) When using the T420's 4-20 mADC test points, best accuracy is achieved by using DVM's with a burden voltage less than 5.0 mV/mA (i.e 5 ohm sense resistance). If using a DVM with a higher sense resistance the installing technician should calibrate by intercepting the 4-20 mADC current loop.
- 2) There are 2.3067 feet per PSI. Use this number (2.3067) in your equations.
- 3) The sensor has a 4 VDC span and a 0.5 VDC offset. The Max% is used to calculate the percentage of the 4 VDC span the sensor will output. This "reduced span" is added to the sensor's offset for the FSO (Full Scale Output).